

# Time-Space Lower Bound for Parity Learning

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Machine Learning Project Presentation  
April 9th 2018

# Learning Parity

A **secret** vector  $\mathbf{s} = (s_1, \dots, s_n) \in \{0, 1\}^n$ .



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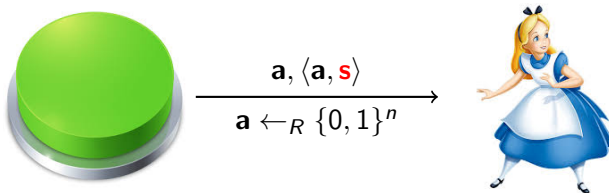
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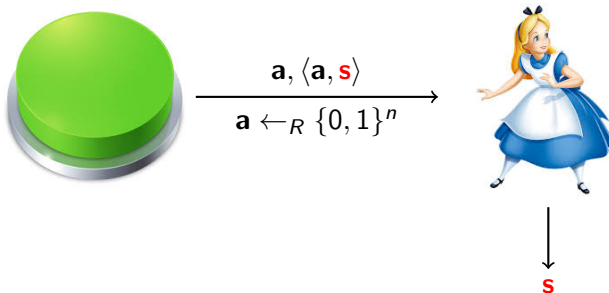
$$\langle \mathbf{x}, \mathbf{y} \rangle = \sum_{i=1}^n x_i y_i \bmod 2$$



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# Learning Parity: Two strategies

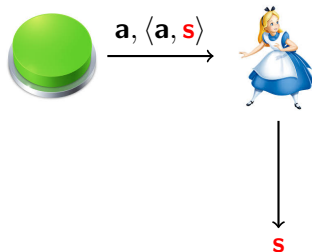
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With **large memory**:

Gather  $n$  vectors  $\mathbf{a}$  into an invertible  $\mathbf{A}$ ,  
→ obtain  $(\mathbf{A}, \mathbf{A} \cdot \mathbf{s})$

Then use **Gaussian Elimination**:

→  $\sim n$  samples and  $n^2$  memory



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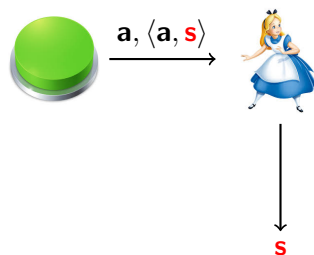
Then use **Gaussian Elimination**:

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With **a lot of samples**:

Wait for a sample  $\mathbf{a} = (1, 0, \dots, 0)$ ;  
**read**  $s_1 = \langle \mathbf{a}, \mathbf{s} \rangle$ .

→  $\sim n \cdot 2^n$  samples and  $n$  memory



# Time-Memory Tradeoff for Learning Parity

- Those are the **only two** strategies!

## Main Theorem ([Raz, FOCS'16] , informal)

Any algorithm that learns parity either:

- Uses  $\sim n^2$  **memory**,

**OR**

- Uses an **exponential number of samples**.



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For all  $c < 1/20$ , there exists an  $\alpha > 0$  such that **any** program using

- $\leq 2^{\alpha n}$  **samples**
- $\leq cn^2$  **memory**

only succeeds with probability  $\leq \mathcal{O}(2^{-\alpha n})$ .

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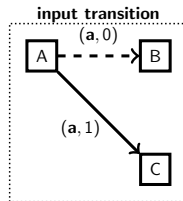
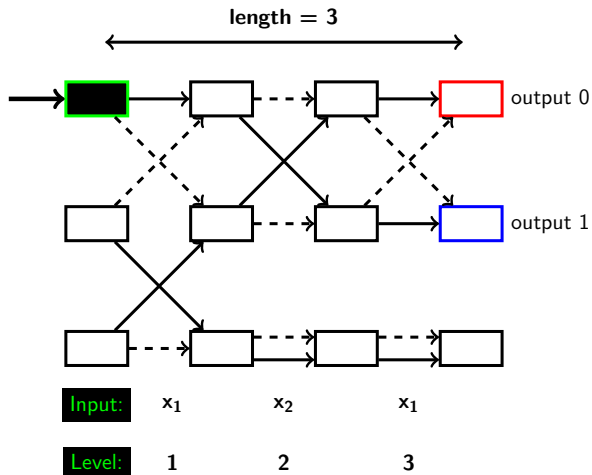
**OR**

- Uses an **exponential number of samples**.

- Proof?

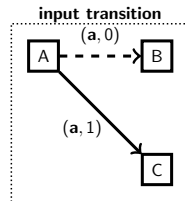
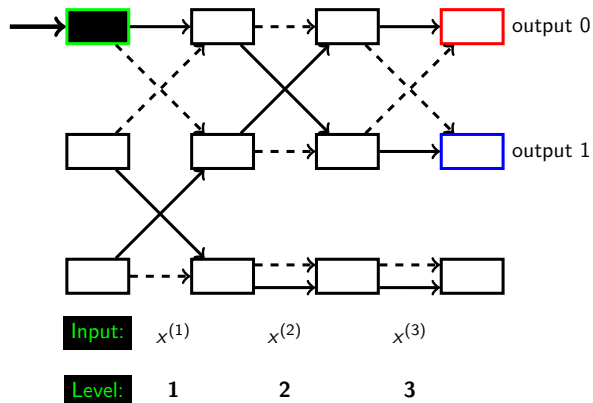
Need a computational model for **bounded memory**.

# Branching Programs



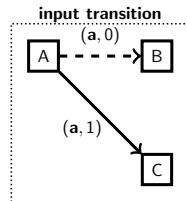
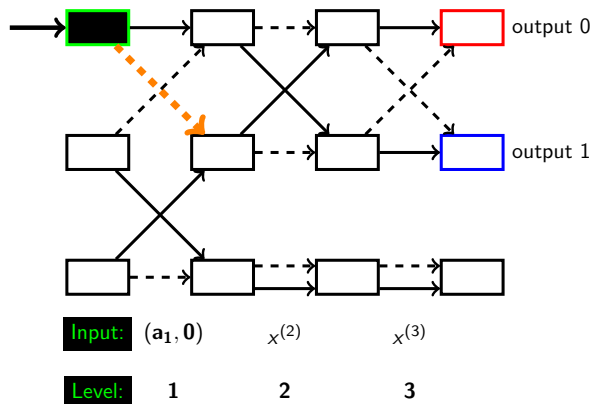
# Branching Programs

Input:  $x^{(1)} = (\mathbf{a}_1, 0)$



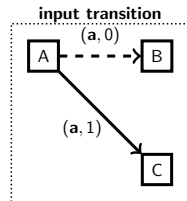
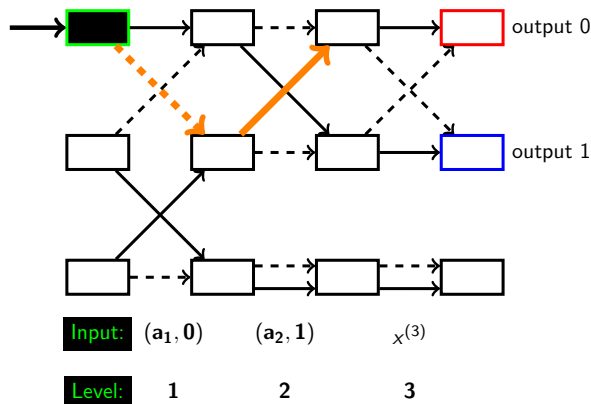
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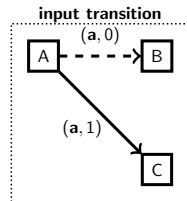
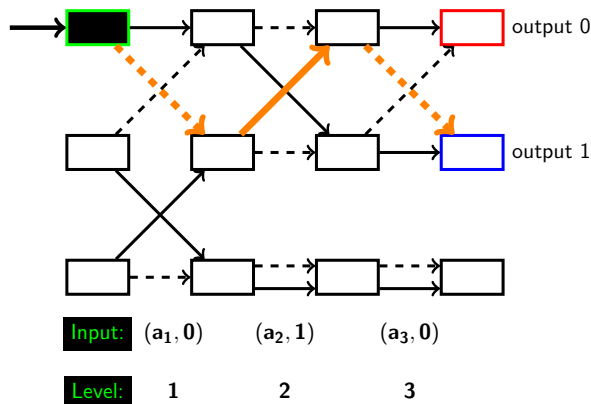
# Branching Programs

Input:  $x^{(2)} = (a_2, 1)$



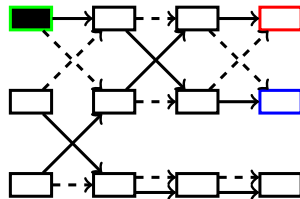
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Input:  $x^{(3)} = (\mathbf{a}_3, 0)$



# Affine Branching Programs

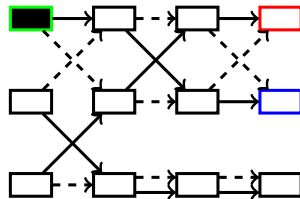
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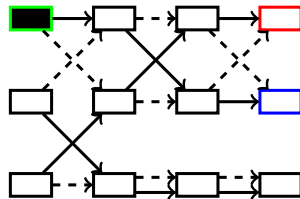
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- Associate **nodes** with **affine subspaces**.
  - Starting node is **the whole space**.

$$E_{start} = \{0, 1\}^n.$$



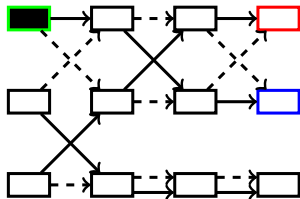
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- Edge  $(u, v)$  for input  $(\mathbf{a}, b)$ ,  
Restricts **s** to a **smaller subspace**.

$$E_v \supseteq E_u \cap \{\mathbf{s} \mid \langle \mathbf{a}, \mathbf{s} \rangle = b\}$$



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The proof goes in two steps:

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## Step 2, much harder

Any **Branching Program** can be simulated by an **Affine Branching Program**.

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Follow-up works: ([Kol-Raz-Tal, STOC'17], [Raz, FOCS'17], [Garg-Raz-Tal, STOC'18]...)

- Generalize lower-bound for **larger class of problems**
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Thank you for your attention